

CONTEXT-FREE LANGUAGES

In Chapter 1 we introduced two different, though equivalent, methods of describing languages: *finite automata* and *regular expressions*. We showed that many languages can be described in this way but that some simple languages, such as $\{0^n 1^n | n \ge 0\}$, cannot.

In this chapter we present *context-free grammars*, a more powerful method of describing languages. Such grammars can describe certain features that have a recursive structure, which makes them useful in a variety of applications.

Context-free grammars were first used in the study of human languages. One way of understanding the relationship of terms such as *noun*, *verb*, and *preposition* and their respective phrases leads to a natural recursion because noun phrases may appear inside verb phrases and vice versa. Context-free grammars help us organize and understand these relationships.

An important application of context-free grammars occurs in the specification and compilation of programming languages. A grammar for a programming language often appears as a reference for people trying to learn the language syntax. Designers of compilers and interpreters for programming languages often start by obtaining a grammar for the language. Most compilers and interpreters contain a component called a *parser* that extracts the meaning of a program prior to generating the compiled code or performing the interpreted execution. A number of methodologies facilitate the construction of a parser once a context-free grammar is available. Some tools even automatically generate the parser from the grammar.

The collection of languages associated with context-free grammars are called the *context-free languages*. They include all the regular languages and many additional languages. In this chapter, we give a formal definition of context-free grammars and study the properties of context-free languages. We also introduce *pushdown automata*, a class of machines recognizing the context-free languages. Pushdown automata are useful because they allow us to gain additional insight into the power of context-free grammars.

2.1

CONTEXT-FREE GRAMMARS

The following is an example of a context-free grammar, which we call G_1 .

$$\begin{array}{l} A \rightarrow 0A1 \\ A \rightarrow B \\ B \rightarrow \texttt{#} \end{array}$$

A grammar consists of a collection of *substitution rules*, also called *productions*. Each rule appears as a line in the grammar, comprising a symbol and a string separated by an arrow. The symbol is called a *variable*. The string consists of variables and other symbols called *terminals*. The variable symbols often are represented by capital letters. The terminals are analogous to the input alphabet and often are represented by lowercase letters, numbers, or special symbols. One variable is designated as the *start variable*. It usually occurs on the left-hand side of the topmost rule. For example, grammar G_1 contains three rules. G_1 's variables are A and B, where A is the start variable. Its terminals are 0, 1, and #.

You use a grammar to describe a language by generating each string of that language in the following manner.

- 1. Write down the start variable. It is the variable on the left-hand side of the top rule, unless specified otherwise.
- 2. Find a variable that is written down and a rule that starts with that variable. Replace the written down variable with the right-hand side of that rule.
- 3. Repeat step 2 until no variables remain.

For example, grammar G_1 generates the string 000#111. The sequence of substitutions to obtain a string is called a *derivation*. A derivation of string 000#111 in grammar G_1 is

 $A \Rightarrow 0A1 \Rightarrow 00A11 \Rightarrow 000A111 \Rightarrow 000B111 \Rightarrow 000\#111.$

You may also represent the same information pictorially with a *parse tree*. An example of a parse tree is shown in Figure 2.1.



FIGURE 2.1 Parse tree for 000#111 in grammar G_1

All strings generated in this way constitute the *language of the grammar*. We write $L(G_1)$ for the language of grammar G_1 . Some experimentation with the grammar G_1 shows us that $L(G_1)$ is $\{0^n \# 1^n | n \ge 0\}$. Any language that can be generated by some context-free grammar is called a *context-free language* (CFL). For convenience when presenting a context-free grammar, we abbreviate several rules with the same left-hand variable, such as $A \to 0A1$ and $A \to B$, into a single line $A \to 0A1 | B$, using the symbol " | " as an "or".

The following is a second example of a context-free grammar, called G_2 , which describes a fragment of the English language.

```
\begin{array}{l} \langle \text{SENTENCE} \rangle \rightarrow \langle \text{NOUN-PHRASE} \rangle \langle \text{VERB-PHRASE} \rangle \\ \langle \text{NOUN-PHRASE} \rangle \rightarrow \langle \text{CMPLX-NOUN} \rangle \mid \langle \text{CMPLX-NOUN} \rangle \langle \text{PREP-PHRASE} \rangle \\ \langle \text{VERB-PHRASE} \rangle \rightarrow \langle \text{CMPLX-VERB} \rangle \mid \langle \text{CMPLX-VERB} \rangle \langle \text{PREP-PHRASE} \rangle \\ \langle \text{PREP-PHRASE} \rangle \rightarrow \langle \text{PREP} \rangle \langle \text{CMPLX-NOUN} \rangle \\ \langle \text{CMPLX-NOUN} \rangle \rightarrow \langle \text{ARTICLE} \rangle \langle \text{NOUN} \rangle \\ \langle \text{CMPLX-VERB} \rangle \rightarrow \langle \text{VERB} \rangle \mid \langle \text{VERB} \rangle \langle \text{NOUN-PHRASE} \rangle \\ \langle \text{ARTICLE} \rangle \rightarrow \mathbf{a} \mid \mathbf{the} \\ \langle \text{NOUN} \rangle \rightarrow \mathbf{boy} \mid \mathbf{girl} \mid \mathbf{flower} \\ \langle \text{VERB} \rangle \rightarrow \mathbf{touches} \mid \mathbf{likes} \mid \mathbf{sees} \\ \langle \text{PREP} \rangle \rightarrow \mathbf{with} \end{array}
```

Grammar G_2 has 10 variables (the capitalized grammatical terms written inside brackets); 27 terminals (the standard English alphabet plus a space character); and 18 rules. Strings in $L(G_2)$ include:

a boy sees the boy sees a flower a girl with a flower likes the boy

Each of these strings has a derivation in grammar G_2 . The following is a derivation of the first string on this list.

$$\langle \text{SENTENCE} \rangle \Rightarrow \langle \text{NOUN-PHRASE} \rangle \langle \text{VERB-PHRASE} \rangle \Rightarrow \langle \text{CMPLX-NOUN} \rangle \langle \text{VERB-PHRASE} \rangle \Rightarrow \langle \text{ARTICLE} \rangle \langle \text{NOUN} \rangle \langle \text{VERB-PHRASE} \rangle \Rightarrow a \langle \text{NOUN} \rangle \langle \text{VERB-PHRASE} \rangle \Rightarrow a boy \langle \text{VERB-PHRASE} \rangle \Rightarrow a boy \langle \text{CMPLX-VERB} \rangle \Rightarrow a boy \langle \text{VERB} \rangle \Rightarrow a boy sees$$

FORMAL DEFINITION OF A CONTEXT-FREE GRAMMAR

Let's formalize our notion of a context-free grammar (CFG).

DEFINITION 2.2

A *context-free grammar* is a 4-tuple (V, Σ, R, S) , where

- 1. V is a finite set called the *variables*,
- **2.** Σ is a finite set, disjoint from *V*, called the *terminals*,
- **3.** *R* is a finite set of *rules*, with each rule being a variable and a string of variables and terminals, and
- **4.** $S \in V$ is the start variable.

If u, v, and w are strings of variables and terminals, and $A \to w$ is a rule of the grammar, we say that uAv yields uwv, written $uAv \Rightarrow uwv$. Say that u derives v, written $u \stackrel{*}{\Rightarrow} v$, if u = v or if a sequence u_1, u_2, \ldots, u_k exists for $k \ge 0$ and

$$u \Rightarrow u_1 \Rightarrow u_2 \Rightarrow \ldots \Rightarrow u_k \Rightarrow v.$$

The *language of the grammar* is $\{w \in \Sigma^* | S \stackrel{*}{\Rightarrow} w\}$.

In grammar G_1 , $V = \{A, B\}$, $\Sigma = \{0, 1, \#\}$, S = A, and R is the collection of the three rules appearing on page 102. In grammar G_2 ,

$$V = \{ \langle \text{SENTENCE} \rangle, \langle \text{NOUN-PHRASE} \rangle, \langle \text{VERB-PHRASE} \rangle, \\ \langle \text{PREP-PHRASE} \rangle, \langle \text{CMPLX-NOUN} \rangle, \langle \text{CMPLX-VERB} \rangle, \\ \langle \text{ARTICLE} \rangle, \langle \text{NOUN} \rangle, \langle \text{VERB} \rangle, \langle \text{PREP} \rangle \}, \end{cases}$$

and $\Sigma = \{a, b, c, ..., z, ""\}$. The symbol "" is the blank symbol, placed invisibly after each word (a, boy, etc.), so the words won't run together.

Often we specify a grammar by writing down only its rules. We can identify the variables as the symbols that appear on the left-hand side of the rules and the terminals as the remaining symbols. By convention, the start variable is the variable on the left-hand side of the first rule.

EXAMPLES OF CONTEXT-FREE GRAMMARS

EXAMPLE 2.3

Consider grammar $G_3 = (\{S\}, \{a, b\}, R, S)$. The set of rules, R, is

 $S \rightarrow aSb \mid SS \mid \epsilon.$

This grammar generates strings such as abab, aaabbb, and aababb. You can see more easily what this language is if you think of a as a left parenthesis "(" and b as a right parenthesis ")". Viewed in this way, $L(G_3)$ is the language of all strings of properly nested parentheses. Observe that the right-hand side of a rule may be the empty string ε .

EXAMPLE **2.4**

Consider grammar $G_4 = (V, \Sigma, R, \langle EXPR \rangle)$. V is $\{\langle EXPR \rangle, \langle TERM \rangle, \langle FACTOR \rangle\}$ and Σ is $\{a, +, x, (,)\}$. The rules are $\langle EXPR \rangle \rightarrow \langle EXPR \rangle + \langle TERM \rangle | \langle TERM \rangle$ $\langle TERM \rangle \rightarrow \langle TERM \rangle \times \langle FACTOR \rangle | \langle FACTOR \rangle$ $\langle FACTOR \rangle \rightarrow (\langle EXPR \rangle) | a$

The two strings a+axa and (a+a)xa can be generated with grammar G_4 . The parse trees are shown in the following figure.





A compiler translates code written in a programming language into another form, usually one more suitable for execution. To do so, the compiler extracts

the meaning of the code to be compiled in a process called *parsing*. One representation of this meaning is the parse tree for the code, in the context-free grammar for the programming language. We discuss an algorithm that parses context-free languages later in Theorem 7.16 and in Problem 7.45.

Grammar G_4 describes a fragment of a programming language concerned with arithmetic expressions. Observe how the parse trees in Figure 2.5 "group" the operations. The tree for $a+a\times a$ groups the \times operator and its operands (the second two a's) as one operand of the + operator. In the tree for $(a+a)\times a$, the grouping is reversed. These groupings fit the standard precedence of multiplication before addition and the use of parentheses to override the standard precedence. Grammar G_4 is designed to capture these precedence relations.

DESIGNING CONTEXT-FREE GRAMMARS

As with the design of finite automata, discussed in Section 1.1 (page 41), the design of context-free grammars requires creativity. Indeed, context-free grammars are even trickier to construct than finite automata because we are more accustomed to programming a machine for specific tasks than we are to describing languages with grammars. The following techniques are helpful, singly or in combination, when you're faced with the problem of constructing a CFG.

First, many CFLs are the union of simpler CFLs. If you must construct a CFG for a CFL that you can break into simpler pieces, do so and then construct individual grammars for each piece. These individual grammars can be easily merged into a grammar for the original language by combining their rules and then adding the new rule $S \rightarrow S_1 | S_2 | \cdots | S_k$, where the variables S_i are the start variables for the individual grammars. Solving several simpler problems is often easier than solving one complicated problem.

For example, to get a grammar for the language $\{0^n 1^n | n \ge 0\} \cup \{1^n 0^n | n \ge 0\}$, first construct the grammar

$$S_1 \rightarrow 0S_1 \mathbf{1} \mid \boldsymbol{\varepsilon}$$

for the language $\{0^n 1^n | n \ge 0\}$ and the grammar

$$S_2
ightarrow 1S_2$$
0 | $arepsilon$

for the language $\{1^n 0^n | n \ge 0\}$ and then add the rule $S \to S_1 | S_2$ to give the grammar

$$egin{array}{c} S
ightarrow S_1 \mid S_2 \ S_1
ightarrow 0S_1 1 \mid arepsilon \ S_2
ightarrow 1S_2 0 \mid arepsilon \end{array}$$

Second, constructing a CFG for a language that happens to be regular is easy if you can first construct a DFA for that language. You can convert any DFA into an equivalent CFG as follows. Make a variable R_i for each state q_i of the DFA. Add the rule $R_i \rightarrow aR_j$ to the CFG if $\delta(q_i, a) = q_j$ is a transition in the DFA. Add the rule $R_i \rightarrow \varepsilon$ if q_i is an accept state of the DFA. Make R_0 the start variable of the grammar, where q_0 is the start state of the machine. Verify on your own that the resulting CFG generates the same language that the DFA recognizes.

Third, certain context-free languages contain strings with two substrings that are "linked" in the sense that a machine for such a language would need to remember an unbounded amount of information about one of the substrings to verify that it corresponds properly to the other substring. This situation occurs in the language $\{0^n 1^n | n \ge 0\}$ because a machine would need to remember the number of 0s in order to verify that it equals the number of 1s. You can construct a CFG to handle this situation by using a rule of the form $R \rightarrow uRv$, which generates strings wherein the portion containing the *u*'s corresponds to the portion containing the *v*'s.

Finally, in more complex languages, the strings may contain certain structures that appear recursively as part of other (or the same) structures. That situation occurs in the grammar that generates arithmetic expressions in Example 2.4. Any time the symbol a appears, an entire parenthesized expression might appear recursively instead. To achieve this effect, place the variable symbol generating the structure in the location of the rules corresponding to where that structure may recursively appear.

AMBIGUITY

Sometimes a grammar can generate the same string in several different ways. Such a string will have several different parse trees and thus several different meanings. This result may be undesirable for certain applications, such as programming languages, where a program should have a unique interpretation.

If a grammar generates the same string in several different ways, we say that the string is derived *ambiguously* in that grammar. If a grammar generates some string ambiguously, we say that the grammar is *ambiguous*.

For example, consider grammar G_5 :

 $\langle \text{EXPR} \rangle \rightarrow \langle \text{EXPR} \rangle + \langle \text{EXPR} \rangle | \langle \text{EXPR} \rangle \times \langle \text{EXPR} \rangle | (\langle \text{EXPR} \rangle) | a$

This grammar generates the string $a+a \times a$ ambiguously. The following figure shows the two different parse trees.



FIGURE **2.6**

The two parse trees for the string $a+a \times a$ in grammar G_5

This grammar doesn't capture the usual precedence relations and so may group the + before the × or vice versa. In contrast, grammar G_4 generates exactly the same language, but every generated string has a unique parse tree. Hence G_4 is unambiguous, whereas G_5 is ambiguous.

Grammar G_2 (page 103) is another example of an ambiguous grammar. The sentence the girl touches the boy with the flower has two different derivations. In Exercise 2.8 you are asked to give the two parse trees and observe their correspondence with the two different ways to read that sentence.

Now we formalize the notion of ambiguity. When we say that a grammar generates a string ambiguously, we mean that the string has two different parse trees, not two different derivations. Two derivations may differ merely in the order in which they replace variables yet not in their overall structure. To concentrate on structure, we define a type of derivation that replaces variables in a fixed order. A derivation of a string w in a grammar G is a *leftmost derivation* if at every step the leftmost remaining variable is the one replaced. The derivation preceding Definition 2.2 (page 104) is a leftmost derivation.

DEFINITION 2.7

A string w is derived *ambiguously* in context-free grammar G if it has two or more different leftmost derivations. Grammar G is *ambiguous* if it generates some string ambiguously.

Sometimes when we have an ambiguous grammar we can find an unambiguous grammar that generates the same language. Some context-free languages, however, can be generated only by ambiguous grammars. Such languages are called *inherently ambiguous*. Problem 2.29 asks you to prove that the language $\{a^ib^jc^k | i = j \text{ or } j = k\}$ is inherently ambiguous.

CHOMSKY NORMAL FORM

When working with context-free grammars, it is often convenient to have them in simplified form. One of the simplest and most useful forms is called the Chomsky normal form. Chomsky normal form is useful in giving algorithms for working with context-free grammars, as we do in Chapters 4 and 7.

DEFINITION 2.8

A context-free grammar is in *Chomsky normal form* if every rule is of the form

 $\begin{array}{c} A \to BC \\ A \to a \end{array}$

where a is any terminal and A, B, and C are any variables—except that B and C may not be the start variable. In addition, we permit the rule $S \rightarrow \varepsilon$, where S is the start variable.

THEOREM 2.9

Any context-free language is generated by a context-free grammar in Chomsky normal form.

PROOF IDEA We can convert any grammar G into Chomsky normal form. The conversion has several stages wherein rules that violate the conditions are replaced with equivalent ones that are satisfactory. First, we add a new start variable. Then, we eliminate all ε -rules of the form $A \rightarrow \varepsilon$. We also eliminate all *unit rules* of the form $A \rightarrow B$. In both cases we patch up the grammar to be sure that it still generates the same language. Finally, we convert the remaining rules into the proper form.

PROOF First, we add a new start variable S_0 and the rule $S_0 \rightarrow S$, where S was the original start variable. This change guarantees that the start variable doesn't occur on the right-hand side of a rule.

Second, we take care of all ε -rules. We remove an ε -rule $A \to \varepsilon$, where A is not the start variable. Then for each occurrence of an A on the right-hand side of a rule, we add a new rule with that occurrence deleted. In other words, if $R \to uAv$ is a rule in which u and v are strings of variables and terminals, we add rule $R \to uv$. We do so for each *occurrence* of an A, so the rule $R \to uAvAw$ causes us to add $R \to uvAw$, $R \to uAvw$, and $R \to uvw$. If we have the rule $R \to A$, we add $R \to \varepsilon$ unless we had previously removed the rule $R \to \varepsilon$. We repeat these steps until we eliminate all ε -rules not involving the start variable.

Third, we handle all unit rules. We remove a unit rule $A \rightarrow B$. Then, whenever a rule $B \rightarrow u$ appears, we add the rule $A \rightarrow u$ unless this was a unit rule previously removed. As before, u is a string of variables and terminals. We repeat these steps until we eliminate all unit rules.

Finally, we convert all remaining rules into the proper form. We replace each rule $A \rightarrow u_1 u_2 \cdots u_k$, where $k \geq 3$ and each u_i is a variable or terminal symbol,

with the rules $A \to u_1 A_1$, $A_1 \to u_2 A_2$, $A_2 \to u_3 A_3$, ..., and $A_{k-2} \to u_{k-1} u_k$. The A_i 's are new variables. We replace any terminal u_i in the preceding rule(s) with the new variable U_i and add the rule $U_i \to u_i$.

.....

EXAMPLE 2.10

Let G_6 be the following CFG and convert it to Chomsky normal form by using the conversion procedure just given. The series of grammars presented illustrates the steps in the conversion. Rules shown in bold have just been added. Rules shown in gray have just been removed.

1. The original CFG G_6 is shown on the left. The result of applying the first step to make a new start variable appears on the right.

$S \rightarrow ASA \mid 2B$	$S_0 ightarrow S$			
$S \rightarrow ASA \mid aD$	$S o ASA \mid$ a B			
$A \to B \mid S$	$A \rightarrow B \mid S$			
$B \rightarrow \mathbf{b} \mid \boldsymbol{\varepsilon}$	$A \rightarrow D \mid S$			
	$B ightarrow b \mid oldsymbol{arepsilon}$			

2. Remove ε -rules $B \to \varepsilon$, shown on the left, and $A \to \varepsilon$, shown on the right.

$S_0 o S$	$S_0 \rightarrow S$
$S ightarrow ASA \mid \mathbf{a}B \mid \mathbf{a}$	$S ightarrow ASA \mid \mathbf{a}B \mid \mathbf{a} \mid oldsymbol{SA} \mid oldsymbol{AS} \mid oldsymbol{S}$
$A \to B \mid S \mid \boldsymbol{\varepsilon}$	$A \to B \mid S \mid \varepsilon$
$B \rightarrow \mathbf{b} \mid \boldsymbol{\varepsilon}$	$B ightarrow { t b}$

3a. Remove unit rules $S \to S$, shown on the left, and $S_0 \to S$, shown on the right.

 $\begin{array}{lll} S_0 \rightarrow S & & S_0 \rightarrow S \mid ASA \mid \mathbf{a}B \mid \mathbf{a} \mid SA \mid AS \\ S \rightarrow ASA \mid \mathbf{a}B \mid \mathbf{a} \mid SA \mid AS \mid S & S \rightarrow ASA \mid \mathbf{a}B \mid \mathbf{a} \mid SA \mid AS \\ A \rightarrow B \mid S & & A \rightarrow B \mid S \\ B \rightarrow \mathbf{b} & & B \rightarrow \mathbf{b} \end{array}$

3b. Remove unit rules $A \rightarrow B$ and $A \rightarrow S$.

$S_0 \rightarrow ASA \mid aB \mid a \mid SA \mid AS$	$S_0 ightarrow ASA \mid {\tt a}B \mid {\tt a} \mid SA \mid AS$
$S ightarrow ASA \mid aB \mid a \mid SA \mid AS$	$S ightarrow ASA \mid aB \mid a \mid SA \mid AS$
$A ightarrow oldsymbol{B} \mid S \mid \mathbf{b}$	$A ightarrow S \mid extbf{b} \mid oldsymbol{ASA} \mid extbf{a}B \mid extbf{a} \mid oldsymbol{SA} \mid oldsymbol{AS}$
$B ightarrow {\tt b}$	$B ightarrow \mathtt{b}$

4. Convert the remaining rules into the proper form by adding additional variables and rules. The final grammar in Chomsky normal form is equivalent to G_6 . (Actually the procedure given in Theorem 2.9 produces several variables U_i and several rules $U_i \rightarrow a$. We simplified the resulting grammar by using a single variable U and rule $U \rightarrow a$.)

$$\begin{array}{l} S_0 \rightarrow AA_1 \mid UB \mid \mathbf{a} \mid SA \mid AS \\ S \rightarrow AA_1 \mid UB \mid \mathbf{a} \mid SA \mid AS \\ A \rightarrow \mathbf{b} \mid AA_1 \mid UB \mid \mathbf{a} \mid SA \mid AS \\ A_1 \rightarrow SA \\ U \rightarrow \mathbf{a} \\ B \rightarrow \mathbf{b} \end{array}$$

2.2

PUSHDOWN AUTOMATA

In this section we introduce a new type of computational model called *pushdown automata*. These automata are like nondeterministic finite automata but have an extra component called a *stack*. The stack provides additional memory beyond the finite amount available in the control. The stack allows pushdown automata to recognize some nonregular languages.

Pushdown automata are equivalent in power to context-free grammars. This equivalence is useful because it gives us two options for proving that a language is context free. We can give either a context-free grammar generating it or a pushdown automaton recognizing it. Certain languages are more easily described in terms of generators, whereas others are more easily described by recognizers.

The following figure is a schematic representation of a finite automaton. The control represents the states and transition function, the tape contains the input string, and the arrow represents the input head, pointing at the next input symbol to be read.



FIGURE 2.11 Schematic of a finite automaton

Copyright 2012 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it.

With the addition of a stack component we obtain a schematic representation of a pushdown automaton, as shown in the following figure.



FIGURE 2.12 Schematic of a pushdown automaton

A pushdown automaton (PDA) can write symbols on the stack and read them back later. Writing a symbol "pushes down" all the other symbols on the stack. At any time the symbol on the top of the stack can be read and removed. The remaining symbols then move back up. Writing a symbol on the stack is often referred to as *pushing* the symbol, and removing a symbol is referred to as *popping* it. Note that all access to the stack, for both reading and writing, may be done only at the top. In other words a stack is a "last in, first out" storage device. If certain information is written on the stack and additional information is written afterward, the earlier information becomes inaccessible until the later information is removed.

Plates on a cafeteria serving counter illustrate a stack. The stack of plates rests on a spring so that when a new plate is placed on top of the stack, the plates below it move down. The stack on a pushdown automaton is like a stack of plates, with each plate having a symbol written on it.

A stack is valuable because it can hold an unlimited amount of information. Recall that a finite automaton is unable to recognize the language $\{0^n 1^n | n \ge 0\}$ because it cannot store very large numbers in its finite memory. A PDA is able to recognize this language because it can use its stack to store the number of 0s it has seen. Thus the unlimited nature of a stack allows the PDA to store numbers of unbounded size. The following informal description shows how the automaton for this language works.

Read symbols from the input. As each 0 is read, push it onto the stack. As soon as 1s are seen, pop a 0 off the stack for each 1 read. If reading the input is finished exactly when the stack becomes empty of 0s, accept the input. If the stack becomes empty while 1s remain or if the 1s are finished while the stack still contains 0s or if any 0s appear in the input following 1s, reject the input.

As mentioned earlier, pushdown automata may be nondeterministic. Deterministic and nondeterministic pushdown automata are *not* equivalent in power. Nondeterministic pushdown automata recognize certain languages that no deterministic pushdown automata can recognize, as we will see in Section 2.4. We give languages requiring nondeterminism in Examples 2.16 and 2.18. Recall that deterministic and nondeterministic finite automata do recognize the same class of languages, so the pushdown automata situation is different. We focus on nondeterministic pushdown automata because these automata are equivalent in power to context-free grammars.

FORMAL DEFINITION OF A PUSHDOWN AUTOMATON

The formal definition of a pushdown automaton is similar to that of a finite automaton, except for the stack. The stack is a device containing symbols drawn from some alphabet. The machine may use different alphabets for its input and its stack, so now we specify both an input alphabet Σ and a stack alphabet Γ .

At the heart of any formal definition of an automaton is the transition function, which describes its behavior. Recall that $\Sigma_{\varepsilon} = \Sigma \cup \{\varepsilon\}$ and $\Gamma_{\varepsilon} = \Gamma \cup \{\varepsilon\}$. The domain of the transition function is $Q \times \Sigma_{\varepsilon} \times \Gamma_{\varepsilon}$. Thus the current state, next input symbol read, and top symbol of the stack determine the next move of a pushdown automaton. Either symbol may be ε , causing the machine to move without reading a symbol from the input or without reading a symbol from the stack.

For the range of the transition function we need to consider what to allow the automaton to do when it is in a particular situation. It may enter some new state and possibly write a symbol on the top of the stack. The function δ can indicate this action by returning a member of Q together with a member of Γ_{ε} , that is, a member of $Q \times \Gamma_{\varepsilon}$. Because we allow nondeterminism in this model, a situation may have several legal next moves. The transition function incorporates nondeterminism in the usual way, by returning a set of members of $Q \times \Gamma_{\varepsilon}$, that is, a member of $\mathcal{P}(Q \times \Gamma_{\varepsilon})$. Putting it all together, our transition function δ takes the form $\delta: Q \times \Sigma_{\varepsilon} \times \Gamma_{\varepsilon} \longrightarrow \mathcal{P}(Q \times \Gamma_{\varepsilon})$.

DEFINITION 2.13

A *pushdown automaton* is a 6-tuple $(Q, \Sigma, \Gamma, \delta, q_0, F)$, where Q, Σ , Γ , and F are all finite sets, and

- 1. Q is the set of states,
- **2.** Σ is the input alphabet,
- **3.** Γ is the stack alphabet,
- **4.** $\delta: Q \times \Sigma_{\varepsilon} \times \Gamma_{\varepsilon} \longrightarrow \mathcal{P}(Q \times \Gamma_{\varepsilon})$ is the transition function,
- **5.** $q_0 \in Q$ is the start state, and
- **6.** $F \subseteq Q$ is the set of accept states.

A pushdown automaton $M = (Q, \Sigma, \Gamma, \delta, q_0, F)$ computes as follows. It accepts input w if w can be written as $w = w_1 w_2 \cdots w_m$, where each $w_i \in \Sigma_{\varepsilon}$ and sequences of states $r_0, r_1, \ldots, r_m \in Q$ and strings $s_0, s_1, \ldots, s_m \in \Gamma^*$ exist that satisfy the following three conditions. The strings s_i represent the sequence of stack contents that M has on the accepting branch of the computation.

- **1.** $r_0 = q_0$ and $s_0 = \epsilon$. This condition signifies that M starts out properly, in the start state and with an empty stack.
- **2.** For i = 0, ..., m 1, we have $(r_{i+1}, b) \in \delta(r_i, w_{i+1}, a)$, where $s_i = at$ and $s_{i+1} = bt$ for some $a, b \in \Gamma_{\varepsilon}$ and $t \in \Gamma^*$. This condition states that M moves properly according to the state, stack, and next input symbol.
- **3.** $r_m \in F$. This condition states that an accept state occurs at the input end.

EXAMPLES OF PUSHDOWN AUTOMATA

......

EXAMPLE **2.14**

The following is the formal description of the PDA (page 112) that recognizes the language $\{0^n 1^n | n \ge 0\}$. Let M_1 be $(Q, \Sigma, \Gamma, \delta, q_1, F)$, where

$$egin{aligned} Q &= \{q_1, q_2, q_3, q_4\}, \ \Sigma &= \{0, 1\}, \ \Gamma &= \{0, \$\}, \ F &= \{q_1, q_4\}, ext{ and } \end{aligned}$$

 δ is given by the following table, wherein blank entries signify \emptyset .

Input:	0		1		ε				
Stack:	0	\$	ε	0	\$	ε	0	\$	ε
q_1									$\{(q_2, \$)\}$
q_2			$\{(q_2,0)\}$	$\{(q_3, oldsymbol{arepsilon})\}$					
q_3				$\{(q_3, \boldsymbol{\varepsilon})\}$				$\{(q_4, \boldsymbol{\varepsilon})\}$	
q_4									

We can also use a state diagram to describe a PDA, as in Figures 2.15, 2.17, and 2.19. Such diagrams are similar to the state diagrams used to describe finite automata, modified to show how the PDA uses its stack when going from state to state. We write " $a,b \rightarrow c$ " to signify that when the machine is reading an a from the input, it may replace the symbol b on the top of the stack with a c. Any of a, b, and c may be ε . If a is ε , the machine may make this transition without reading and popping any symbol from the stack. If c is ε , the machine does not write any symbol on the stack when going along this transition.



FIGURE **2.15** State diagram for the PDA M_1 that recognizes $\{0^n 1^n | n \ge 0\}$

The formal definition of a PDA contains no explicit mechanism to allow the PDA to test for an empty stack. This PDA is able to get the same effect by initially placing a special symbol \$ on the stack. Then if it ever sees the \$ again, it knows that the stack effectively is empty. Subsequently, when we refer to testing for an empty stack in an informal description of a PDA, we implement the procedure in the same way.

Similarly, PDAs cannot test explicitly for having reached the end of the input string. This PDA is able to achieve that effect because the accept state takes effect only when the machine is at the end of the input. Thus from now on, we assume that PDAs can test for the end of the input, and we know that we can implement it in the same manner.

EXAMPLE **2.16**

This example illustrates a pushdown automaton that recognizes the language

$$\{\mathbf{a}^i \mathbf{b}^j \mathbf{c}^k | i, j, k \ge 0 \text{ and } i = j \text{ or } i = k\}.$$

Informally, the PDA for this language works by first reading and pushing the a's. When the a's are done, the machine has all of them on the stack so that it can match, them with either the b's or the c's. This maneuver is a bit tricky because the machine doesn't know in advance whether to match the a's with the b's or the c's. Nondeterminism comes in handy here.

Using its nondeterminism, the PDA can guess whether to match the a's with the b's or with the c's, as shown in Figure 2.17. Think of the machine as having two branches of its nondeterminism, one for each possible guess. If either of them matches, that branch accepts and the entire machine accepts. Problem 2.57 asks you to show that nondeterminism is essential for recognizing this language with a PDA.



FIGURE **2.17** State diagram for PDA M_2 that recognizes $\{\mathbf{a}^i \mathbf{b}^j \mathbf{c}^k | i, j, k \ge 0 \text{ and } i = j \text{ or } i = k\}$

EXAMPLE 2.18 ------

In this example we give a PDA M_3 recognizing the language $\{ww^{\mathcal{R}} | w \in \{0,1\}^*\}$. Recall that $w^{\mathcal{R}}$ means w written backwards. The informal description and state diagram of the PDA follow.

Begin by pushing the symbols that are read onto the stack. At each point, nondeterministically guess that the middle of the string has been reached and then change into popping off the stack for each symbol read, checking to see that they are the same. If they were always the same symbol and the stack empties at the same time as the input is finished, accept; otherwise reject.



FIGURE **2.19**

State diagram for the PDA M_3 that recognizes $\{ww^{\mathcal{R}} | w \in \{0,1\}^*\}$

Problem 2.58 shows that this language requires a nondeterministic PDA.

EQUIVALENCE WITH CONTEXT-FREE GRAMMARS

In this section we show that context-free grammars and pushdown automata are equivalent in power. Both are capable of describing the class of context-free languages. We show how to convert any context-free grammar into a pushdown automaton that recognizes the same language and vice versa. Recalling that we defined a context-free language to be any language that can be described with a context-free grammar, our objective is the following theorem.

THEOREM 2.20

A language is context free if and only if some pushdown automaton recognizes it.

As usual for "if and only if" theorems, we have two directions to prove. In this theorem, both directions are interesting. First, we do the easier forward direction.

LEMMA 2.21 ------

If a language is context free, then some pushdown automaton recognizes it.

PROOF IDEA Let A be a CFL. From the definition we know that A has a CFG, G, generating it. We show how to convert G into an equivalent PDA, which we call P.

The PDA P that we now describe will work by accepting its input w, if G generates that input, by determining whether there is a derivation for w. Recall that a derivation is simply the sequence of substitutions made as a grammar generates a string. Each step of the derivation yields an *intermediate string* of variables and terminals. We design P to determine whether some series of substitutions using the rules of G can lead from the start variable to w.

One of the difficulties in testing whether there is a derivation for w is in figuring out which substitutions to make. The PDA's nondeterminism allows it to guess the sequence of correct substitutions. At each step of the derivation, one of the rules for a particular variable is selected nondeterministically and used to substitute for that variable.

The PDA P begins by writing the start variable on its stack. It goes through a series of intermediate strings, making one substitution after another. Eventually it may arrive at a string that contains only terminal symbols, meaning that it has used the grammar to derive a string. Then P accepts if this string is identical to the string it has received as input.

Implementing this strategy on a PDA requires one additional idea. We need to see how the PDA stores the intermediate strings as it goes from one to another. Simply using the stack for storing each intermediate string is tempting. However, that doesn't quite work because the PDA needs to find the variables in the intermediate string and make substitutions. The PDA can access only the top

symbol on the stack and that may be a terminal symbol instead of a variable. The way around this problem is to keep only *part* of the intermediate string on the stack: the symbols starting with the first variable in the intermediate string. Any terminal symbols appearing before the first variable are matched immediately with symbols in the input string. The following figure shows the PDA *P*.



FIGURE **2.22**

P representing the intermediate string 01A1A0

The following is an informal description of P.

- 1. Place the marker symbol \$ and the start variable on the stack.
- 2. Repeat the following steps forever.
 - **a.** If the top of stack is a variable symbol *A*, nondeterministically select one of the rules for *A* and substitute *A* by the string on the right-hand side of the rule.
 - **b.** If the top of stack is a terminal symbol *a*, read the next symbol from the input and compare it to *a*. If they match, repeat. If they do not match, reject on this branch of the nondeterminism.
 - **c.** If the top of stack is the symbol \$, enter the accept state. Doing so accepts the input if it has all been read.

PROOF We now give the formal details of the construction of the pushdown automaton $P = (Q, \Sigma, \Gamma, \delta, q_{\text{start}}, F)$. To make the construction clearer, we use shorthand notation for the transition function. This notation provides a way to write an entire string on the stack in one step of the machine. We can simulate this action by introducing additional states to write the string one symbol at a time, as implemented in the following formal construction.

Let q and r be states of the PDA and let a be in Σ_{ε} and s be in Γ_{ε} . Say that we want the PDA to go from q to r when it reads a and pops s. Furthermore, we want it to push the entire string $u = u_1 \cdots u_l$ on the stack at the same time. We can implement this action by introducing new states q_1, \ldots, q_{l-1} and setting the transition function as follows:

$$\delta(q, a, s) \text{ to contain } (q_1, u_l)$$

$$\delta(q_1, \varepsilon, \varepsilon) = \{(q_2, u_{l-1})\},$$

$$\delta(q_2, \varepsilon, \varepsilon) = \{(q_3, u_{l-2})\},$$

$$\vdots$$

$$\delta(q_{l-1}, \varepsilon, \varepsilon) = \{(r, u_1)\}.$$

We use the notation $(r, u) \in \delta(q, a, s)$ to mean that when q is the state of the automaton, a is the next input symbol, and s is the symbol on the top of the stack, the PDA may read the a and pop the s, then push the string u onto the stack and go on to the state r. The following figure shows this implementation.



FIGURE **2.23** Implementing the shorthand $(r, xyz) \in \delta(q, a, s)$

The states of P are $Q = \{q_{\text{start}}, q_{\text{loop}}, q_{\text{accept}}\} \cup E$, where E is the set of states we need for implementing the shorthand just described. The start state is q_{start} . The only accept state is q_{accept} .

The transition function is defined as follows. We begin by initializing the stack to contain the symbols \$ and S, implementing step 1 in the informal description: $\delta(q_{\text{start}}, \boldsymbol{\epsilon}, \boldsymbol{\epsilon}) = \{(q_{\text{loop}}, S^{\text{start}})\}$. Then we put in transitions for the main loop of step 2.

First, we handle case (a) wherein the top of the stack contains a variable. Let $\delta(q_{\text{loop}}, \varepsilon, A) = \{(q_{\text{loop}}, w) | \text{ where } A \to w \text{ is a rule in } R\}.$

Second, we handle case (b) wherein the top of the stack contains a terminal. Let $\delta(q_{\text{loop}}, a, a) = \{(q_{\text{loop}}, \varepsilon)\}.$

Finally, we handle case (c) wherein the empty stack marker \$ is on the top of the stack. Let $\delta(q_{\text{loop}}, \varepsilon, \$) = \{(q_{\text{accept}}, \varepsilon)\}.$

The state diagram is shown in Figure 2.24.

Copyright 2012 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it.



FIGURE 2.24 State diagram of *P*

That completes the proof of Lemma 2.21.

EXAMPLE 2.25

We use the procedure developed in Lemma 2.21 to construct a PDA P_1 from the following CFG G.

$$S \rightarrow aTb \mid b$$

 $T \rightarrow Ta \mid \varepsilon$

The transition function is shown in the following diagram.



State diagram of P_1

Now we prove the reverse direction of Theorem 2.20. For the forward direction, we gave a procedure for converting a CFG into a PDA. The main idea was to design the automaton so that it simulates the grammar. Now we want to give a procedure for going the other way: converting a PDA into a CFG. We design the grammar to simulate the automaton. This task is challenging because "programming" an automaton is easier than "programming" a grammar.

LEMMA **2.27**

If a pushdown automaton recognizes some language, then it is context free.

PROOF IDEA We have a PDA P, and we want to make a CFG G that generates all the strings that P accepts. In other words, G should generate a string if that string causes the PDA to go from its start state to an accept state.

To achieve this outcome, we design a grammar that does somewhat more. For each pair of states p and q in P, the grammar will have a variable A_{pq} . This variable generates all the strings that can take P from p with an empty stack to q with an empty stack. Observe that such strings can also take P from p to q, regardless of the stack contents at p, leaving the stack at q in the same condition as it was at p.

First, we simplify our task by modifying P slightly to give it the following three features.

- **1.** It has a single accept state, q_{accept} .
- **2.** It empties its stack before accepting.
- **3.** Each transition either pushes a symbol onto the stack (a *push* move) or pops one off the stack (a *pop* move), but it does not do both at the same time.

Giving P features 1 and 2 is easy. To give it feature 3, we replace each transition that simultaneously pops and pushes with a two transition sequence that goes through a new state, and we replace each transition that neither pops nor pushes with a two transition sequence that pushes then pops an arbitrary stack symbol.

To design G so that A_{pq} generates all strings that take P from p to q, starting and ending with an empty stack, we must understand how P operates on these strings. For any such string x, P's first move on x must be a push, because every move is either a push or a pop and P can't pop an empty stack. Similarly, the last move on x must be a pop because the stack ends up empty.

Two possibilities occur during P's computation on x. Either the symbol popped at the end is the symbol that was pushed at the beginning, or not. If so, the stack could be empty only at the beginning and end of P's computation on x. If not, the initially pushed symbol must get popped at some point before the end of x and thus the stack becomes empty at this point. We simulate the former possibility with the rule $A_{pq} \rightarrow aA_{rs}b$, where a is the input read at the first move, b is the input read at the last move, r is the state following p, and s is the state preceding q. We simulate the latter possibility with the rule $A_{pq} \rightarrow A_{pr}A_{rq}$, where r is the state when the stack becomes empty.

PROOF Say that $P = (Q, \Sigma, \Gamma, \delta, q_0, \{q_{\text{accept}}\})$ and construct G. The variables of G are $\{A_{pq} | p, q \in Q\}$. The start variable is $A_{q_0,q_{\text{accept}}}$. Now we describe G's rules in three parts.

- **1.** For each $p, q, r, s \in Q$, $u \in \Gamma$, and $a, b \in \Sigma_{\varepsilon}$, if $\delta(p, a, \varepsilon)$ contains (r, u) and $\delta(s, b, u)$ contains (q, ε) , put the rule $A_{pq} \to aA_{rs}b$ in G.
- **2.** For each $p, q, r \in Q$, put the rule $A_{pq} \rightarrow A_{pr}A_{rq}$ in G.
- **3.** Finally, for each $p \in Q$, put the rule $A_{pp} \to \varepsilon$ in G.

You may gain some insight for this construction from the following figures.









Copyright 2012 Cengage Learning. All Rights Reserved. May not be copied, scanned, or duplicated, in whole or in part. Due to electronic rights, some third party content may be suppressed from the eBook and/or eChapter(s). Editorial review has deemed that any suppressed content does not materially affect the overall learning experience. Cengage Learning reserves the right to remove additional content at any time if subsequent rights restrictions require it.

Now we prove that this construction works by demonstrating that A_{pq} generates x if and only if (iff) x can bring P from p with empty stack to q with empty stack. We consider each direction of the iff as a separate claim.

CLAIM 2.30

If A_{pq} generates x, then x can bring P from p with empty stack to q with empty stack.

We prove this claim by induction on the number of steps in the derivation of x from A_{pq} .

Basis: The derivation has 1 step.

A derivation with a single step must use a rule whose right-hand side contains no variables. The only rules in G where no variables occur on the right-hand side are $A_{pp} \rightarrow \epsilon$. Clearly, input ϵ takes P from p with empty stack to p with empty stack so the basis is proved.

Induction step: Assume true for derivations of length at most k, where $k \ge 1$, and prove true for derivations of length k + 1.

Suppose that $A_{pq} \stackrel{*}{\Rightarrow} x$ with k + 1 steps. The first step in this derivation is either $A_{pq} \Rightarrow aA_{rs}b$ or $A_{pq} \Rightarrow A_{pr}A_{rq}$. We handle these two cases separately.

In the first case, consider the portion y of x that A_{rs} generates, so x = ayb. Because $A_{rs} \stackrel{*}{\Rightarrow} y$ with k steps, the induction hypothesis tells us that P can go from r on empty stack to s on empty stack. Because $A_{pq} \rightarrow aA_{rs}b$ is a rule of $G, \delta(p, a, \varepsilon)$ contains (r, u) and $\delta(s, b, u)$ contains (q, ε) , for some stack symbol u. Hence, if P starts at p with empty stack, after reading a it can go to state rand push u onto the stack. Then reading string y can bring it to s and leave uon the stack. Then after reading b it can go to state q and pop u off the stack. Therefore, x can bring it from p with empty stack to q with empty stack.

In the second case, consider the portions y and z of x that A_{pr} and A_{rq} respectively generate, so x = yz. Because $A_{pr} \stackrel{*}{\Rightarrow} y$ in at most k steps and $A_{rq} \stackrel{*}{\Rightarrow} z$ in at most k steps, the induction hypothesis tells us that y can bring P from p to r, and z can bring P from r to q, with empty stacks at the beginning and end. Hence x can bring it from p with empty stack to q with empty stack. This completes the induction step.

CLAIM 2.31

If x can bring P from p with empty stack to q with empty stack, A_{pq} generates x.

We prove this claim by induction on the number of steps in the computation of P that goes from p to q with empty stacks on input x.

Basis: The computation has 0 steps.

If a computation has 0 steps, it starts and ends at the same state—say, p. So we must show that $A_{pp} \stackrel{*}{\Rightarrow} x$. In 0 steps, P cannot read any characters, so $x = \varepsilon$. By construction, G has the rule $A_{pp} \rightarrow \varepsilon$, so the basis is proved.

Induction step: Assume true for computations of length at most k, where $k \ge 0$, and prove true for computations of length k + 1.

Suppose that P has a computation wherein x brings p to q with empty stacks in k + 1 steps. Either the stack is empty only at the beginning and end of this computation, or it becomes empty elsewhere, too.

In the first case, the symbol that is pushed at the first move must be the same as the symbol that is popped at the last move. Call this symbol u. Let a be the input read in the first move, b be the input read in the last move, r be the state after the first move, and s be the state before the last move. Then $\delta(p, a, \varepsilon)$ contains (r, u) and $\delta(s, b, u)$ contains (q, ε) , and so rule $A_{pq} \rightarrow aA_{rs}b$ is in G.

Let y be the portion of x without a and b, so x = ayb. Input y can bring P from r to s without touching the symbol u that is on the stack and so P can go from r with an empty stack to s with an empty stack on input y. We have removed the first and last steps of the k + 1 steps in the original computation on x so the computation on y has (k + 1) - 2 = k - 1 steps. Thus the induction hypothesis tells us that $A_{rs} \stackrel{*}{\Rightarrow} y$. Hence $A_{pq} \stackrel{*}{\Rightarrow} x$.

In the second case, let r be a state where the stack becomes empty other than at the beginning or end of the computation on x. Then the portions of the computation from p to r and from r to q each contain at most k steps. Say that y is the input read during the first portion and z is the input read during the second portion. The induction hypothesis tells us that $A_{pr} \stackrel{*}{\Rightarrow} y$ and $A_{rq} \stackrel{*}{\Rightarrow} z$. Because rule $A_{pq} \rightarrow A_{pr}A_{rq}$ is in G, $A_{pq} \stackrel{*}{\Rightarrow} x$, and the proof is complete.

That completes the proof of Lemma 2.27 and of Theorem 2.20.

We have just proved that pushdown automata recognize the class of contextfree languages. This proof allows us to establish a relationship between the regular languages and the context-free languages. Because every regular language is recognized by a finite automaton and every finite automaton is automatically a pushdown automaton that simply ignores its stack, we now know that every regular language is also a context-free language.

COROLLARY 2.32

Every regular language is context free.